Document No. RWM002040-AN-en IEC60870 Master Protocol - Annex1 IEC60870-5-101 - V1.1



IEC60870-5-101

The IEC60870 is an international standard for system monitoring and telecontrol in utilities for water distribution, gas and electricity distribution and energy power system. The RightWON IEC60870 stack supports both IEC60870-5-101 (serial) and IEC60870-5-104 (TCP/IP) slaves.

In the last few years, especially in the energy sector, a protocol standard has established itself which is now considered a "must-have" in substation automation and which is supported by virtually every component producer. We are talking about the international standards 60870-5-101 for serial communication, published in 1995 by the IEC, and 60870-5-104 for communication via TCP/IP, published in 2000.

Both protocols are identical on the application layer, this means they have the same reference data structure. Thanks to that, the configuration and implementation for both serial communication [-101] and TCP/IP networks [-104] is an unique configuration tool in the RightWON Configuration Suite.

The protocol IEC 60870-5-10x defines that messages and values must be sent spontaneously from Slave (Controller) to Master (PC) after a change, so there is no Polling procedure. After establishing the connection, the master sends a "general interrogation command" to the slave in order to get the current state of all data points. From this time on, the Slave watches for changes of the data points and sends only if required.



Configuration of IEC60870-5-101 in the RightWON Configuration Suite

The RightWON Configuration Suite provides an integrated configuration tool for the IEC60870-5-101 master based on the Driver Development Kit. The result is a transparent integration of this additional Fieldbus in the PLC IEC 61131-3 programming environment.

In the serial case, the Suite works as the master in unbalanced communication mode.

IEC60870 Master

- Channel
 - Session
 - Variables

IEC60870-5-101 master:

Property	Description
Log Traces	Display messages in the output

Channel:

Property	Description
Connection name	Name of the connection
Mode	Select serial or Ethernet connection
Address	For ETHERNET mode, IP address of the server For SERIAL mode, description of the serial port: "COM1:9600,N,8,1"
Connection Timeout	Link connection Timeout (Default 3s)
Diagnostic	Diagnostic options

Session:

Property	Description
Session ID	Identifier of the session (Number)
Master address	Master address in this session
Link address	Outstation address in this session
Keep alive	Zero not activated or time in ms (Default deactivated)
Integrity interval	Zero for no polling or time in ms (Default 5s)
Event interval	Zero for no polling or time in ms (Default 1s)
APDU/Data size	APDU size (Default 253)
COA size	COA size (Default 1 byte)
COT size	COT size (Default 1 byte)
IOA size	IOA size (Default 1 byte)
Use UTC time base	Use UTS time for timestamp
OEM Diagnostic mask	Diagnostic options (Refer to OEM documentation)

Property	Description	
Symbol	Variable name	
Operation	Read data: Get the data value	
	Error report: 0 if ok	
CAOA	Common address	
TID	Type identifier	
IOA	Object address	
Туре	(1) Binary inputs	
	(3) Double inputs	
	(10) Binary Output Status	
	(20) Running Counters	
	(20) Frozen Counters	
	(30) Analog inputs	
	(40) Analog Output Status	
	(110) String Data	

Variables:

Note: Variable status and time stamp are stored in the RightWON database if the option is activated and if the variable has a defined profile. Please refer to the section Variable status bits in the RightWON Configuration Suite online help.



Implementation of IEC 60870-5-101 driver in the RightWON Configuration Suite

According to the configuration, the IEC60870-5-101 driver will establish the connection and open all sessions. The refresh of data can be automatic according to the parameters in the Session.

Additional command are available, these commands are function blocks in the RightWON Configuration Suite with the Session identifier as the first parameters.

Command:

Name	Description
Commands are function blocks	 Input parameters: Send: Send command Session: Session Identifier Command: Select, Operate, DirectOperate, DirectOperateNoAck CACOA: point TID IOA
	Output parameters: • Done • Status: Integer



Interoperability

This companion standard presents sets of parameters and alternatives from which subsets must be selected to implement particular telecontrol systems. Certain parameter values, such as the choice of 'structured' or 'unstructured' fields of the information object address of ASDUs represent mutually exclusive alternatives. This means that only one value of the defined parameters is admitted per system. Other parameters, such as the listed set of different process information in command and in monitor direction allow the specification of the complete set or subsets, as appropriate for given applications. This clause summarizes the parameters of the previous clauses to facilitate a suitable selection for a specific application. If a system is composed of equipment stemming from different manufacturers, it is necessary that all partners agree on the selected parameters.

The interoperability list is defined as in IEC60870-5-101 and extended with parameters used in this standard. The text descriptions of parameters which are not applicable to this companion standard are strike-through (corresponding check box is marked black).

NOTE: In addition, the full specification of a system may require individual selection of certain parameters for certain parts of the system, such as the individual selection of scaling factors for individually addressable measured values.

The selected parameters should be marked in the white boxes as follows:

- [] Function or ASDU is not used
- [X] Function or ASDU is used as standardized (default)
- [R] Function or ASDU is used in reverse mode
- [B] Function or ASDU is used in standard and reverse mode

The possible selection (blank, X, R, or B) is specified for each specific clause or parameter. A black check box indicates that the option cannot be selected in this companion standard.

4.1. System or device

(system-specific parameter, indicate definition of a system or a device by marking one of the following with 'X')

[] System definition

[X] Controlling station definition (Master)

[]Controlled station definition (Slave)

4.2. Network Configuration

(network-specific parameter, all configurations that are used are to be marked 'X')

[X] Point-to-point	[X] Multipoint-partyline
[X] Multiple point to point	[] Multipoint-star

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4.3. Physical Layer

(network-specific parameter, all interfaces and data rates that are used are to be marked 'X')

nced interchange uit X.24/X.27
400 bit/s 800 bit/s 600 bit/s 9200 bit/s 8400 bit/s 6000 bit/s

4.3.1. Transmission speed (control direction)

4.3.2. Transmission speed (monitor direction)

Unbalanced interchange Circuit V.24/V.28 Standard	Unbalanced interchange Circuit V.24/V.28 Recommended if >1 200 bit/s	Balanced interchange Circuit X.24/X.27
[X] 100 bit/s [X] 200 bit/s [X] 300 bit/s [X] 600 bit/s [X] 1200 bit/s	[X] 2400 bit/s [X] 4800 bit/s [X] 9600 bit/s	[] 2400 bit/s [] 4800 bit/s [] 9600 bit/s [] 19200 bit/s [] 38400 bit/s [] 56000 bit/s [] 64000 bit/s

4.4. Link layer

(network-specific parameter, all options that are used are to be marked 'X'. Specify the maximum frame length. If a non-standard assignment of class 2 messages is implemented for unbalanced transmission, indicate the Type ID and COT of all messages assigned to class 2.)

Frame format FT 1.2, single character 1 and the fixed time out interval are used exclusively in this companion standard.

Link transmission	Frame length [octets]	Address field of the link
[] Balanced transmission	[255] Maximum length L	[] not present
	(number of octets)	(balanced transmission only)
[X] Unbalanced transmission		[X] One octet
		[X] Two octets
		[X] Structured
		[X] Unstructured

When using an unbalanced link layer, the following ASDU types are returned in class 2 messages (low priority) with the indicated causes of transmission:

[] The standard assignment of ASDUs to class 2 messages is used as follows:

Type identification	Cause of transmission
9, 11, 13, 21	<1>
[X] A special assignment of ASDUs to	o class 2 messages is used as follows:
Type identification	Cause of transmission

Note: (In response to a class 2 poll, a controlled station may respond with class 1 data when there is no class 2 data available).

4.5. Application Layer

4.5.1. Transmission mode for application data

Mode 1 (Least significant octet first), as defined in 4.10 of IEC60870-5-4, is used exclusively in this companion standard.

4.5.2. Common address of ASDU

(System-specific parameter, all configurations that are used are to be marked 'X')

ASDU Adress	
[X] One octet	[X] Two octet

4.5.3. Information object address

(System-specific parameter, all configurations that are used are to be marked 'X')

ASDU Adress	
[X] Two octets	[X] Unstructured
[X] Tree octets	

4.5.4. Cause of transmission

(system-specific parameter, all configurations that are used are to be marked 'X')

Cause of transmission	
[X] One octet	[X] Two octet (with originator address)
	Originator address is set to zero if not used.

4.5.5. Length of APDU: 104 only

(system-specific parameter, all configurations that are used are to be marked 'X') The maximum length of the APDU is 253 (default). The maximum length may be reduced by the system.

[] Maximum length of APDU per system

4.5.6. Selection of standard ASDUs

4.5.6.1. Process information in monitor direction

(station-specific parameter, mark each Type ID 'X' if it is only used in the standard direction, 'R' if only used in the reverse direction, and 'B' if used in both directions).

Mark	Parameter	Туре
[X]	<1>: = Single-point information	M_SP_NA_1
[X]	<2>: = Single-point information with time tag	M_SP_TA_1
[X]	<3>: = Double-point information	M_DP_NA_1
[X]	<4>: = Double-point information with time tag	M_DP_TA_1
[X]	<5>: = Step position information	M_ST_NA_1
[X]	<6>: = Step position information with time tag	M_ST_TA_1
[X]	<7>: = Bitstring of 32 bit	M_BO_NA_1
[X]	<8>: = Bitstring of 32 bit with time tag	M_BO_TA_1
[X]	<9>: = Measured value, normalized value	M_ME_NA_1
[X]	<10>: = Measured value, normalized value with time tag	M_ME_TA_1
[X]	<11>: = Measured value, scaled value	M_ME_NB_1

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[X]	<12>: = Measured value, scaled value with time tag	M_ME_TB_1
[B]	<13>: = Measured value, short floating point value	M_ME_NC_1
[B]	<14>: = Measured value, short floating point value with time tag	M_ME_TC_1
[B]	<15>: = Integrated totals	M_IT_NA_1
[B]	<16>: = Integrated totals with time tag	M_IT_TA_1
[]	<17>: = Event of protection equipment with time tag	M_EP_TA_1
[]	<18>: = Packed start events of protection equipment with time tag	M_EP_TB_1
[]	<19>: = Packed output circuit information of protection equipment	M_EP_TC_1
	with time tag	
[]	<20>: = Packed single-point information with status change	M_SP_NA_1
	detection	
[]	<21>: = Measured value, normalized value without quality descriptor	M_ME_ND_1
[X]	<30>: = Single-point information with time tag CP56Time2a	M_SP_TB_1
[X]	<31>: = Double-point information with time tag CP56Time2a	M_DP_TB_1
[X]	<32>: = Step position information with time tag CP56Time2a	M_ST_TB_1
[X]	<33>: = Bitstring of 32 bit with time tag CP56Time2a	M_BO_TB_1
[X]	<34>: = Measured value, normalized value with time tag	M_ME_TD_1
	CP56Time2a	
[X]	<35>: = Measured value, scaled value with time tag CP56Time2a	M_ME_TE_1
[X]	<36>: = Measured value, short floating point value with time tag	M_ME_TF_1
	CP56Time2a	
[X]	<37>: = Integrated totals with time tag CP56Time2a	M_IT_TB_1
[]	<38>: = Event of protection equipment with time tag CP56Time2a	M_EP_TD_1
[]	<39>: = Packed start events of protection equipment with time tag	M_EP_TE_1
	CP56Time2a	
[]	<40>:= Packed output circuit information of protection equipment	M_EP_TF_1
	with time tag CP56Time2a	

Either the ASDUs of the set <2>, <4>, <6>, <8>, <10>, <12>, <14>, <16>, <17>, <18>, <19> or of the set <30> - <40> are used.

4.5.6.2. Process information in control direction

(station-specific parameter, mark each Type ID 'X' if it is only used in the standard direction, 'R' if only used in the reverse direction, and 'B' if used in both directions).

Mark	Parameter	Туре
[X]	<45>: = Single command	C_SC_NA_1
[X]	<46>: = Double command	C_DC_NA_1
[X]	<47>: = Regulating step command	C_RC_NA_1
[X]	<48>: = Set point command, normalized value	C_SE_NA_1
[X]	<49>: = Set point command, scaled value	C_SE_NB_1
[X]	<50>: = Set point command, short floating point value	C_SE_NC_1
[X]	<51>: = Bitstring of 32 bit	C_BO_NA_1
[X]	<58>: = Single command with time tag CP56Time2a	C_SC_TA_1
[X]	<59>: = Double command with time tag CP56Time2a	C_DC_TA_1
[X]	<60>: = Regulating step command with time tag CP56Time2a	C_RC_TA_1
[X]	<61>: = Set point command, normalized value with time tag	C_SE_TA_1
	CP56Time2a	
[X]	<62>: = Set point command, scaled value with time tag CP56Time2a	C_SE_TB_1
[X]	<63>: = Set point command, short floating point value with time tag	C_SE_TC_1
	CP56Time2a	
[X]	<64>:= Bitstring of 32 bit with time tag CP56Time2a	C_BO_TA_1

Either the ASDUs of the set <45> - <51> or of the set <58> - <64> are used.

4.5.6.3. System information in monitor direction

(station-specific parameter, mark 'X' if used)

Mark	Parameter	Туре
[]	<70> : = End of initialization	M_EI_NA_1

4.5.6.4. System information in control direction

(station-specific parameter, mark each Type ID 'X' if it is only used in the standard direction, 'R' if only used in the reverse direction, and 'B' if used in both directions).

Mark	Parameter	Туре
[X]	<100>: = Interrogation command	C_IC_NA_1
[]	<101>: = Counter interrogation command	C_CI_NA_1
[]	<102>: = Read command	C_RD_NA_1
[B]	<103>: = Clock synchronization command	C_CS_NA_1
[]	<104>: = Test command	C_TS_NA_1
[]	<105>: = Reset process command	C_RP_NA_1
[]	<106>: = Delay acquisition command	C_CD_NA_1
[]	<107>: = Test command with time tag CP56Time2a	C_TS_TA_1

4.5.6.5. Parameter in control direction

(station-specific parameter, mark each Type ID 'X' if it is only used in the standard direction, 'R' if only used in the reverse direction, and 'B' if used in both directions).

Mark	Parameter	Туре
[]	<110>: = Parameter of measured value, normalized value	P_ME_NA_1
[]	<111>: = Parameter of measured value, scaled value	P_ME_NB_1
[]	<112>: = Parameter of measured value, short floating point value	P_ME_NC_1
[]	<113>: = Parameter activation	P_AC_NA_1

4.5.6.6. File transfer

(station-specific parameter, mark each Type ID 'X' if it is only used in the standard direction, 'R' if only used in the reverse direction, and 'B' if used in both directions).

Mark	Parameter	Туре
[]	<120>: = File ready	F_FR_NA_1
[]	<121>: = Section ready	F_SR_NA_1
[]	<122>: = Call directory, select file, call file, call section	F_SC_NA_1
[]	<123>: = Last section, last segment	F_LS_NA_1
[]	<124>: = Ack file, ack section	F_AF_NA_1
[]	<125>: = Segment	F_SG_NA_1
[]	<126>: = Directory	F_DR_TA_1
	{blank or X, only available in monitor (standard) direction}	

4.5.6.7. Type identifier and Cause of transmission assignments

(station-specific parameters)

Shaded boxes: option not required.

Black boxes: option not permitted in this companion standard

Blank: functions or ASDU not used.

Mark Type Identification/Cause of transmission combinations:

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Type i	dentification	Cause of transmission																		
		1	2	3	4	5	6	7	8	9	10	11	12	13	20 to 36	to	44	45	46	47
<1>	M_SP_NA_1																			
<2>	M_SP_TA_1																			
<3>	M_DP_NA_1																			
<4>	M_DP_TA_1																			
<5>	M_ST_NA_1																			
<6>	M_ST_TA_1																			
<7>	M_BO_NA_1																			
<8>	M_BO_TA_1																			
<9>	M_ME_NA_1																			
<10>	M_ME_TA_1																			
<11>	M_ME_NB_1																			
<12>	M_ME_TB_1																			
<13>	M_ME_NC_1																			
<14>	M_ME_TC_1																			
<15>	M_IT_NA_1																			
<16>	M_IT_TA_1																			
<17>	M_EP_TA_1																			
<18>	M_EP_TB_1																			
<19>	M_EP_TC_1																			
<20>	M_PS_NA_1																			
<21>	M_ME_ND_1																			
<30>	M_SP_TB_1																			
<31>	M_DP_TB_1																			
<32>	M_ST_TB_1																			
<33>	M_BO_TB_1																			
<34>	M_ME_TD_1																			
<35>	M_ME_TE_1																			
<36>	M_ME_TF_1																			
<37>	M_IT_TB_1																			
<38>	M_EP_TD_1																			
<39>	M_EP_TE_1																			
<40>	M_EP_TF_1																			
<45>	C_SC_NA_1																			
<46>	C_DC_NA_1																			1
<47>	C_RC_NA_1																			
<48>	 C_SE_NA_1										Ì							İ		
<49>	C_SE_NB_1																	Ì		1
<50>	C_SE_NC_1						İ				İ							İ		

'X' if only used in the standard direction; 'R' if only used in the reverse direction; 'B' if used in both directions.

Type id	entification	Cau	ise	of t	ran	smi	ssio	n											
		1	2	3	4	5	6	7	8	9	10	11	12	13	to	44	45	46	47
<51>	C_BO_NA_1																		
<58>	C_SC_TA_1																		
<59>	C_DC_TA_1																		
<60>	C_RC_TA_1																		
<61>	C_SE_TA_1																		
<62>	C_SE_TB_1																		
<63>	C_SE_TC_1																		
<64>	C_BO_TA_1																		
<70>	M_EI_NA_1*																		
<100>	C_IC_NA_1																		
<101>	C_CI_NA_1																		
<102>	C_RD_NA_1																		
<103>	C_CS_NA_1																		
<104>	C_TS_NA_1																		
<105>	C_RP_NA_1																		
<106>	C_CD_NA_1																		
<107>	C_TS_TA_1																		
<110>	P_ME_NA_1																		
<111>	P_ME_NB_1																		
<112>	P_ME_NC_1																		
<113>	P_AC_NA_1																		
<120>	F_FR_NA_1																		
<121>	F_SR_NA_1																		
<122>	F_SC_NA_1																		
<123>	F_LS_NA_1																		
<124>	F_AF_NA_1																		
<125>	F_SG_NA_1																		
<126>	F_DR_TA_1*																		

* Blank or X only

СОТ	Cause of Transmission	
<0>	not used	
<1>	periodic, cyclic	per/cyc
<2>	background scan	back
<3>	spontaneous	spont
<4>	initialized	init
<5>	request or requested	req
<6>	activation	act
<7>	activation confirmation	actcon
<8>	deactivation	deacts
<9>	deactivation confirmation	deactcon

<10>	activation termination	actterm
<11>	return information caused by a remote command	retrem
<12>	return information caused by a local command	retloc
<13>	file transfer	file
<1419>	reserved	
<20>	interrogated by station interrogation	inrogen
<2136>	interrogated by interrogation of the group 116	
<37>	requested by general counter request	reqcogen
<3841>	requested by counter interrogation of the group 1 4	
<42, 43>	reserved	
<44>	unknown type identification	
<45>	unknown cause of transmission	
<46>	unknown common address of ASDU	
<47>	unknown information object address	
<48, 63>	for special use (private range)	

4.6. Basic application functions

4.6.1. Station initialization

(station-specific parameter, mark 'X' if function is used)

[] Remote initialization

4.6.2. Cyclic data transmission

(station-specific parameter, mark 'X' if function is only used in the standard direction, 'R' if only used in the reverse direction, and 'B' if used in both directions)

[X] Cyclic data transmission

4.6.3. Read procedure

(station-specific parameter, mark 'X' if function is only used in the standard direction, 'R' if only used in the reverse direction, and 'B' if used in both directions)

[] Read procedure

4.6.4. Spontaneous transmission

(station-specific parameter, mark 'X' if function is only used in the standard direction, 'R' if only used in the reverse direction, and 'B' if used in both directions)

[X] Spontaneous transmission

4.6.5. Double transmission of information objects with cause of transmission spontaneous

(station-specific parameter, mark each information type 'X' where both a Type ID without time and corresponding Type ID with time are issued in response to a single spontaneous change of a monitored object)

The following type identifications may be transmitted in succession caused by a single status change of an information object. The particular information object addresses for which double transmission is enabled are defined in a project-specific list.

[] Single-point information M_SP_NA_1, M_SP_TA_1, M_SP_TB_1 and M_PS_NA_1

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[] Double-point information M_DP_NA_1, M_DP_TA_1 and M_DP_TB_1

[] Step position information M ST NA 1, M ST TA 1 and M ST TB 1

[] Bitstring of 32 bit M BO NA 1, M BO TA 1 and M BO TB 1 (if defined for a specific project)

[] Measured value, normalized value M_ME_NA_1, M_ME_TA_1, M_ME_ND_1 and M_ME_TD_1

[] Measured value, scaled value M_ME_NB_1, M_ME_TB_1 and M_ME_TE_1

[] Measured value, short floating point number M ME NC 1, M ME TC 1 and M ME TF 1

4.6.6. Station interrogation

(station-specific parameter, mark 'X' if function is only used in the standard direction, 'R' if only used in the reverse direction, and 'B' if used in both directions).

[X] global		
[] group 1	[] group 7	[] group 13
[] group 2	[] group 8	[] group 14
[] group 3	[] group 9	[] group 15
[] group 4	[] group 10	[] group 16
[] group 5	[] group 11	Information object addresses assigned to each group
[] group 6	[] group 12	must be shown in a separate table.

4.6.7. Clock synchronization

(station-specific parameter, mark 'X' if function is only used in the standard direction, 'R' if only used in the reverse direction, and 'B' if used in both directions).

[X] Clock synchronization

4.6.8. Command transmission

(station-specific parameter, mark 'X' if function is only used in the standard direction, 'R' if only used in the reverse direction, and 'B' if used in both directions).

[X] Direct command transmission

[X] Direct set point command transmission

[X] Select and execute command

[X] Select and execute set point command

[] C SE ACTTERM used

[X] No additional definition

[] Short-pulse duration (duration determined by a system parameter in the outstation)

[] Long-pulse duration (duration determined by a system parameter in the outstation)

[] Persistent output

[] Supervision of maximum delay in command direction of commands and set point commands

[] Maximum allowable delay of commands and set point commands

4.6.9. Transmission of integrated totals

(station-specific parameter, mark 'X' if function is only used in the standard direction, 'R' if only used in the reverse direction, and 'B' if used in both directions).

[] Mode A: Local freeze with spontaneous transmission

[] Mode B: Local freeze with counter interrogation

[] Mode C: Freeze and transmit by counter-interrogation commands

[] Mode D: Freeze by counter-interrogation command, frozen values reported spontaneously

[] Counter read

[] Counter freeze without reset

- [] Counter freeze with reset
- [] Counter reset
- [] General request counter
- [] Request counter group 1
- [] Request counter group 2
- [] Request counter group 3
- [] Request counter group 4

4.6.10. Parameter loading

(station-specific parameter, mark 'X' if function is only used in the standard direction, 'R' if only used in the reverse direction, and 'B' if used in both directions).

- [] Threshold value
- [] Smoothing factor
- [] Low limit for transmission of measured values
- [] High limit for transmission of measured values

4.6.11. Parameter activation

(station-specific parameter, mark 'X' if function is only used in the standard direction, 'R' if only used in the reverse direction, and 'B' if used in both directions).

[] Act/deact of persistent cyclic or periodic transmission of the addressed object

4.6.12. Test procedure

(station-specific parameter, mark 'X' if function is only used in the standard direction, 'R' if only used in the reverse direction, and 'B' if used in both directions).

[] Test procedure

4.6.13. File transfer

(station-specific parameter, mark 'X' if function is used).

File transfer in monitor direction

- [] Transparent file
- [] Transmission of disturbance data of protection equipment
- [] Transmission of sequences of events
- [] Transmission of sequences of recorded analogue values

File transfer in control direction

[] Transparent file

4.6.14. Background scan

(station-specific parameter, mark 'X' if function is only used in the standard direction, 'R' if only used in the reverse direction, and 'B' if used in both directions).

[] Background scan

4.6.15. Acquisition of transmission delay

(station-specific parameter, mark 'X' if function is only used in the standard direction, 'R' if only used in the reverse direction, and 'B' if used in both directions).

[] Acquisition of transmission delay

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Parameters	Default value	Remarks	Selected value
t0	30 s	Timeout of connection establishment	not fixed
t1	15 s	Timeout of send or test APDUs	not fixed
t2	10 s	Timeout for acknowledges in case of no data messages; t2 < t1	not fixed
t3	20 s	Timeout for sending test frames in case of a long idle state; $t_3 > t_1$	not fixed

4.6.15.1. Definition of timeouts

Maximum range of values for all time-outs: 1 to 255 s, accuracy 1 s.

4.6.15.2. Maximum number of outstanding I format APDUs (k) and latest acknowledge APDUs (w)

Parameter	Default value	Remarks	Selected value
k		Maximum difference receive sequence number to send state variable	not fixed
w		Latest acknowledge after receiving w I format APDUs	not fixed

Maximum range of values k: 1 to 32767 (215-1) APDUs, accuracy 1 APDU

Maximum range of values w: 1 to 32767 APDUs, accuracy 1 APDU (Recommendation: w should not exceed two-thirds of k)

4.6.15.3. Port number

Parameter	Default value	Remarks
Portnumber	2404	In all cases

4.7. RFC 2200 suite

RFC 2200 is an official Internet Standard which describes the state of standardization of protocols used in the Internet as determined by the Internet Architecture Board (IAB). It offers a broad spectrum of actual standards used in the Internet. The suitable selection of documents from RFC 2200 defined in this standard for given projects has to be chosen by the user of this standard.

[] Ethernet 802.3

[] Serial X.21 interface

[] Other selection from RFC 2200:

List of valid documents from RFC 2200:

1.	
2.	
5.	
	etc.